



1
00:00:04,309 --> 00:00:02,389
and we have confirmation that the

2
00:00:12,150 --> 00:00:04,319
payload retention latch assemblies have

3
00:00:17,109 --> 00:00:14,470
first step will be now that it is free

4
00:00:20,950 --> 00:00:17,119
of endeavour's payload bay to

5
00:00:25,589 --> 00:00:20,960
raise the ams up to a low hover position

6
00:00:29,349 --> 00:00:27,429
once that is established after a couple

7
00:00:32,069 --> 00:00:29,359
of minutes the crew will be given a go

8
00:00:33,830 --> 00:00:32,079
to proceed on with

9
00:00:36,470 --> 00:00:33,840
maneuvering it over

10
00:00:38,389 --> 00:00:36,480
the side of endeavour's payload bay up

11
00:00:41,190 --> 00:00:38,399
toward the international space station

12
00:01:06,390 --> 00:00:41,200
for a handoff to the station's robotic

13
00:01:11,190 --> 00:01:08,630

the shuttle's robotic arm now has the

14

00:01:14,630 --> 00:01:11,200

brakes on it's in the position now for

15

00:01:19,749 --> 00:01:14,640

the handoff next up will be for the

16

00:01:24,710 --> 00:01:22,630

operated by greg shamatoff and greg

17

00:01:27,429 --> 00:01:24,720

johnson

18

00:01:29,990 --> 00:01:27,439

in the uh at the robotic workstation

19

00:01:33,429 --> 00:01:30,000

inside the space station in particular

20

00:01:38,469 --> 00:01:36,630

repositioning the camera views uh

21

00:01:45,109 --> 00:01:38,479

to

22

00:01:51,749 --> 00:01:48,149

the ams as the station's robotic arm

23

00:01:53,109 --> 00:01:51,759

gets ready to maneuver over to the

24

00:01:56,630 --> 00:01:53,119

ams

25

00:01:59,030 --> 00:01:56,640

and capture the other grapple fixture

26

00:02:01,510 --> 00:01:59,040

inside is a

27

00:02:03,270 --> 00:02:01,520

dedicated robotics workstation with its

28

00:02:07,190 --> 00:02:03,280

own screens

29

00:02:10,790 --> 00:02:09,669

see the the same view that you're seeing

30

00:02:12,869 --> 00:02:10,800

here

31

00:02:16,309 --> 00:02:12,879

so that they can align properly before

32

00:02:19,430 --> 00:02:16,319

moving in for grapple and in fact the

33

00:02:21,270 --> 00:02:19,440

the go has been given the arm is now in

34

00:02:46,390 --> 00:02:21,280

the process of being maneuvered in for

35

00:02:51,110 --> 00:02:48,630

and a good capture is confirmed the

36

00:02:52,710 --> 00:02:51,120

station robotic arm now is locked onto

37

00:02:56,150 --> 00:02:52,720

the grapple pin

38

00:02:57,910 --> 00:02:56,160

of the uh alpha magnetic spectrometer

39

00:02:59,910 --> 00:02:57,920

occurring as endeavor in the

40

00:03:03,190 --> 00:02:59,920

international space station track to the

41

00:03:04,550 --> 00:03:03,200

south west of the canary islands

42

00:03:08,790 --> 00:03:04,560

the

43

00:03:19,430 --> 00:03:08,800

ams is being positioned to its uh

44

00:03:24,149 --> 00:03:21,830

and we do now have confirmation of uh

45

00:03:26,789 --> 00:03:24,159

complete of completed capture of the

46

00:03:28,789 --> 00:03:26,799

alpha magnetic spectrometer it's

47

00:03:30,710 --> 00:03:28,799

made its way to its uh

48

00:03:31,750 --> 00:03:30,720

final home on the international space

49

00:03:32,869 --> 00:03:31,760

station

50

00:03:36,070 --> 00:03:32,879

the

